

**Series 6 Solution**

**31 October 2025**

**Exercise 1: Density of dislocations, Frank lattice**

Considering a uniform distribution of the dislocations in three dimensions, we suppose that each dislocation stops on the free surface of the crystal, a cell of dimension  $a$  (average distance between etch-pits).

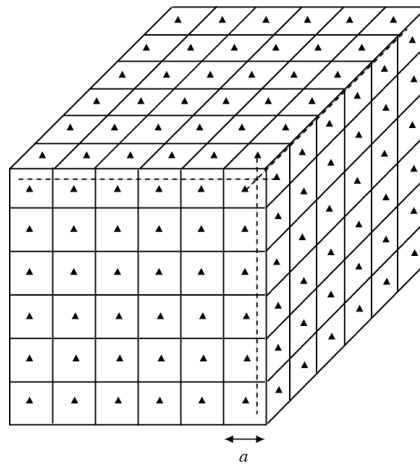


Fig. 6.1 Scheme of the etch pits appearing on each face of the cube

Each cell contains a dislocation length of  $3a$ , and the dislocation density is given by:

$$\Lambda = \frac{3a}{a^3} = \frac{3}{a^2}$$

Application:

$$a = 10\mu m \rightarrow \Lambda = \frac{3}{a^2} = 3 \cdot 10^6 \text{ cm}^{-2}$$

Two planes contain the Burgers vector:  $b = \frac{1}{2}(\bar{1}10)$  and the planes  $(111)$  and  $(\bar{1}\bar{1}1)$

Therefore, the active dislocation density averaged for "2" glide planes is:  $\Lambda_m = \frac{3}{2} \cdot 10^6 \text{ cm}^{-2}$

The Orowan equation is:

$$\epsilon_{max} = \Lambda_m b u_{max}$$

The aluminum structure is f.c.c. The Burgers vector joins two atoms on a dense plane. Supposing that the atomic spheres are tangent in the densely packed directions:

$$b = 2R_{Al} = 2 \cdot 1.43 \text{ \AA} = 2.86 \text{ \AA}$$

We can also calculate  $b$  from the cell parameter:  $a_{Al} = 4.05 \text{ \AA}$   $b = \frac{\sqrt{2}}{2} a = 2.864 \text{ \AA}$

$$\epsilon_{max} = \frac{3}{2} \cdot 10^6 \cdot 2.86 \left[ \frac{1}{cm^2} \right] \cdot 10^{-8} \cdot 1 [cm^2] = 4.3 \cdot 10^{-2} \approx 4\%$$

### Exercise 2: Nabarro-Herring creep

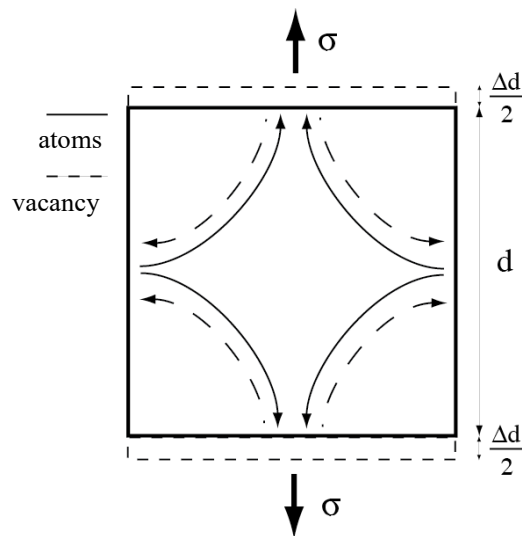


Fig. 6.2 Flux of vacancies and atoms in a grain creeping by internal diffusion

The stress  $\sigma$  generates a flux of atoms toward the surface and vacancies in the opposite direction. The number of atoms brought to the surface per unit of time is:

$$\phi = Jd^2 \tag{6.2.1}$$

a) Calculation of the deformation

If the generated volume per time unit  $\phi \cdot \Omega$  ( $\Omega =$  atomic volume) spreads immediately, it

forms on each side of the cube a layer of thickness  $\frac{\Delta d}{2} = \frac{\phi \Omega t}{d^2}$ . The deformation rate can be expressed as follows:

$$\dot{\epsilon} = \frac{\Delta d}{t} \frac{1}{d} = \frac{1}{d} 2\phi \frac{\Omega}{d^2} = 2\phi \frac{\Omega}{d^3} = 2J \frac{\Omega}{d} \tag{6.2.2}$$

b) Calculation of the atom flux  $J$ :

$$J = v_v C_v \quad C_v = \frac{\text{number of vacancies}}{\text{volume crystal}} = \frac{n_v}{n\Omega} = \frac{X_v}{\Omega} \quad (6.2.3)$$

To calculate  $v_v$ , we consider that the stress causes a transport force  $F$  on the vacancies (Einstein formula).

$$v_v = \frac{D_{mV} F}{kT} \quad (6.2.4)$$

$D_{m\ell}$  is the diffusion coefficient per defect migration.

### c) Forces

If the crystal is deformed to a length  $\Delta d$  and the vacancies are transported on each side by the force  $F$  over a characteristic distance  $\approx \frac{d}{2}$ , the energy balance gives:

$$\sigma \cdot d^2 \cdot \frac{\Delta d}{2} = F \cdot \frac{d}{2} \cdot \text{nb vacancies} = F \cdot \frac{d}{2} \cdot \frac{(\Delta d / 2) \cdot d^2}{\Omega}$$

$$\text{From which we get: } F = \frac{2\sigma\Omega}{d} \quad (6.2.5)$$

Using (6.2.3), (6.2.4) and (6.2.5) we can determine the flux  $J$ :

$$J = \frac{X_v}{\Omega} \frac{D_{mV}}{kT} \frac{2\sigma\Omega}{d} = \frac{D_{sd}}{kT} \frac{2\sigma}{d} \quad (6.2.6)$$

We note that  $X_v D_{mV} = D_{sd}$  is the self-diffusion coefficient (§ 5.3.2).

$$\text{Finally (6.2.1) and (6.2.2) imply: } \dot{\epsilon} = \frac{4D_{sd}}{d^2} \frac{\sigma}{kT} \quad (6.2.7)$$

The creep is Newtonian ( $\dot{\epsilon} \sim \sigma$ ) and depends on the grain size  $d$ , varying with  $\frac{1}{d^2}$ , which can be experimentally verified.